# MATH 5061 Lecture 17 (Mar 31)

fixing end pts

Recall: Y: [a,b] -> (M,g) geodesic (ie. E'(0) =0 Y variation ys)

2nd variation for E: V= 35 | s=0 "Variation"

= (0) = \( \big| \land \big| \land \big| \land \big| \land \big| \land \big| \

my form I(V,W) = [b < Dy,V, Dy,W> - < R(Y',V)Y',V>dt

m) look at the "kernel" of this symmetric bilinear form

Jawbi fields:

 $\nabla_{\mathbf{x}'}\nabla_{\mathbf{x}'}\mathbf{V} + \mathcal{R}(\mathbf{x}',\mathbf{v})\mathbf{Y}' = \mathbf{0}$ 

2nd order linear ODE System.

tangent to Y' & normal to Y'

reparametrization

Contain information

(linear function of Y' int)

about the geometry of (Mig)

### Conjugate points à minimizing geodesiès

Recall: "Ganss Lemma": < => "short" geodesies are (length / energy) minimizing in geodesic normal coord.

Q: What about the "long' geodesics?

A: related to normal Jacobi fields!

Conjugar pt to 📍 minimizing after permy

Idea: A geodesic will fail to be minimizing once it passes through a "conjugate pt.".

the antipodal pt.

Def?: Let Y: [a,b] → (M".g) be a geodesic. We say that Y(a) & Y(b) are conjugate (along Y) if 3 non-trivial Jacobi field of V(t) along & st V(a) = 0 = V(b)Furthermore, we define the multiplicaty as the dimension of the vector space 7(a) of all such V above.

Remark: Since VT is a linear function in to (times V') Vanishing of  $V^T$  at end pts  $\Rightarrow$   $V^T \equiv 0$  (ie the V above must be normal to T') So, multiplicity & n-1

E.g.) (5%, Sround) & Rn+1 Y: [0.7] - (5". 3 mod) great circle Joining antipodat pts. Any rotation in R<sup>n41</sup> fixing Y(0), Y(7)

conjugate
pts generates a Jacobi field V vanishing at the end points by rotations Y(T)

> multiplicaty = n-1

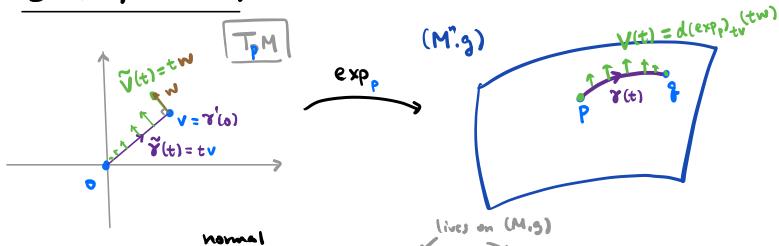
There is a relation between "conjugate points" 4 the "singularities of the exponential map"

Prop: Let 8: [0.1] -> (M.g) be a geodesic joining P=8(0), &=8(1).

THEN. (1) P, & are conjugate along Y

(2)  $V = Y(0) \in TpM$  is a critical pt. of expe ie d(exp<sub>p</sub>), is singular Furthermore, multiplicity = dim (ker (d(exp,))).

#### "IDEA of the Proof":



Observation: Any Jacobi field V(t) along & st V(0) = 0

has the form V(t) = d(exp<sub>e</sub>)<sub>tu</sub>(tw) for some W & V & TpM

Note: w = V (0)

V is a Jacobi field

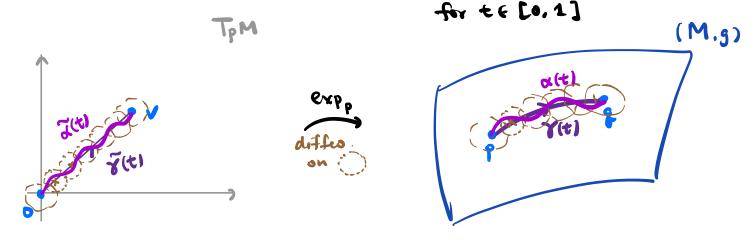
vanishing at the end pts  $(=) V(1) = d(exp_p)_v(w) = 0$ ie W E ker (d (exp.).).

Thm: Let  $Y: (0,1] \rightarrow (M'',g)$  be a geodesic with p=Y(0), q=Y(1).

- (i) If Y(t) is NOT conjugate to Y(0) = P for all te [0.1], then Y is a "locally" minimizing geodesic between the end pts. ie y ame a = y. L(a) > L(x)
- (ii) If 3 to 6 (0,1) st. Y(to) is conjugate to p= Y(o). then 3 variation Vs, fixing the end points P. J. st L(X:) < L(X) 4 small S @ (-8.8)

'Sketch of Proof": Let's start with (i).

By previous Prop. + hypothesis > expp is a local diffeo. at each tv



Gauss lemma => L(a)> L(8)

Now, let's assume the hypothesis in (ii).

Claim:  $\exists v + W(t) \text{ along } X, t \in [0,1], \text{ st } I(W,W) < 0$ ( $\Rightarrow$ ) varietion Ys corresponding to W satisfy the concusion)

Let U(t) be a parellel u.f. along Y. te Co. 1], st

Fix a smooth cutoff for  $\varphi(t): Co.1) \to \mathbb{R}$  st  $\begin{cases} \varphi(0) = \varphi(1) = 0 \\ \varphi(t_0) = 1 \end{cases}$ 

Define: For each of GIR. define (piecewise smooth) v.f. along Y

$$W = W(t) := \begin{cases} V(t) + \alpha Y(t) U(t) & \text{if } t \in [0, t_0] \\ \alpha Y(t) U(t) & \text{if } t \in [t_0, 1] \end{cases}$$

$$I(W,W)$$

$$= \int_{0}^{t_{0}} \langle W', W' \rangle - \langle R(Y',W)Y',W \rangle dt$$

$$+ \int_{t_{0}}^{4} \langle W', W' \rangle - \langle R(Y',W)Y',W \rangle dt$$

$$= \int_{0}^{t_{0}} \langle V', V' \rangle - \langle R(Y',V)Y',V \rangle dt$$

+ 
$$\int_{t_0}^{4} \langle W', W' \rangle - \langle R(Y', W)Y', W \rangle dt$$
=0 : V is Jawhi field  $V(0) = 0 = V(t_0)$ 

$$= \int_0^{t_0} \langle V', V' \rangle - \langle R(Y', V) Y', V \rangle dt$$

+ 
$$2\alpha \int_{0}^{t} \langle v', \varphi'u \rangle - \langle R(v', v)v', \varphi u \rangle dt$$
  
+  $\alpha^{2} \int_{0}^{1} (\varphi')^{2} ||u||^{2} - \langle R(v', \varphi u)v', \varphi u \rangle dt$ 

= 
$$2\alpha < \frac{V'. \Psi u}{t=0}$$
 +  $\alpha^2 I(\Psi u. \Psi u) < 0$  for small  $\alpha$ .

# Riemannian manifold as a metric space

(M°, g): Riemannian manifold (connected)



Define a distance on M as follow: for any P, & E M.

$$d(p, q) := \inf \left\{ L(X) : X : [0, 1] \rightarrow M \text{ precentle smooth } \right\}$$
st  $Y(0) = p$ ,  $Y(1) = q$ 

FACT: (M,d) is a metric space.

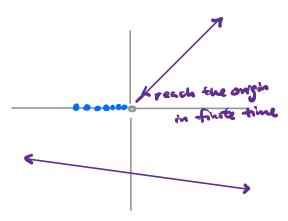
Q: When is it complete as metric space?

In fact, there is a more differential-geometric notion of "completeness".

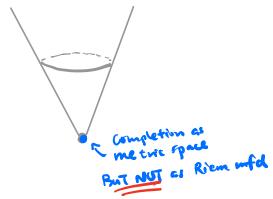
Def!: A Riem. mfd (M".g) is geodesically complete if any geodesic on M can be infinitely extended on both sides (ie defined on all of IR).

#### Examples:

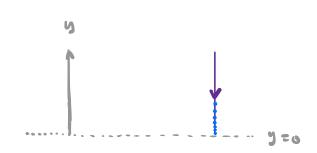
(1) R1 (0) w. flat metric



NOT compute as metric space NOT geodesically compute



NOT complete as meture spece.
NOT geodesically complete



Not (sanderically) complete with Sflat

But (seederically) complete with

hyperbolic  $g_{hyp} := \frac{1}{y^2} (dx^2 + dy^2)$ metric  $g_{hyp} := \frac{1}{y^2} (dx^2 + dy^2)$ 

Hopf-Rinow Theorem: Let (M".g) be a smooth Riem mfd.

THEN, the following are equivalent:

- (4) (M",g) is geodesically complete
- (2) (M, d) is complete as a metric space
- (3) The exponential map at p, expp, is well-defined on the whole TpM, for SOME p = M.
- (4) The exponential map at p, expp, is well-defined on the whole TpM, for ALL pGM.

If any of the above holds, then

(\*) 
$$\forall P, Q \in M, \exists minimizing geodesic  $Y: [0,1] \rightarrow M$   
st.  $Y(0) = P, Y(1) = Q$  and  $L(Y) = d(P,Q)$ .$$

Proof: HW Exercise!